

Binary Response Models for Panel Data

(GB: Chapters 13.8, 15.8)
Isabel Casas

Summary today's class

- ➊ Motivation
- ➋ Without unknown individual effects
 - The linear probability model and panel data
 - Pooled Probit and Logit models for panel data
- ➌ Unobserved Effects Probit (with strict exogeneity)
 - Fixed Effects estimation
 - Random Effects estimation
 - Alternatives (pooled, etc)
- ➍ Unobserved Effects Logit (with strict exogeneity)
 - Random Effects estimation
 - Fixed Effects estimation
- ➎ Dynamic Unobserved Effects Models (without strict exogeneity)

Motivation

- We have previously considered binary response models:
 - LPM
 - Probit models
 - Logit models
- But without a time dimension
- Individuals were observed once
- If observed more than once \Rightarrow panel data
- Panel methods can be applied.

Panel data set

j	t	y_{jt}	x_{jt}^1	x_{jt}^2	\dots	x_{jt}^k
1	1	y_{11}	x_{11}^1	x_{11}^2	\dots	x_{11}^k
1	2	y_{12}	x_{12}^1	x_{12}^2	\dots	x_{12}^k
1	3	y_{13}	x_{13}^1	x_{13}^2	\dots	x_{13}^k
2	1	y_{21}	x_{21}^1	x_{21}^2	\dots	x_{21}^k
2	2	y_{22}	x_{22}^1	x_{22}^2	\dots	x_{22}^k
2	3	y_{23}	x_{23}^1	x_{23}^2	\dots	x_{23}^k
\vdots					\vdots	
n	1	y_{n1}	x_{n1}^1	x_{n1}^2	\dots	x_{n1}^k
n	2	y_{n2}	x_{n2}^1	x_{n2}^2	\dots	x_{n2}^k
n	3	y_{n3}	x_{n3}^1	x_{n3}^2	\dots	x_{n3}^k

$y_{jj} = 1 \text{ or } 0$

Binary models **without** unknown effects

- The linear probability model with panel data
 - Same problem than in the cross-sectional case
- To obtain estimates in $[0,1]$
 - Pooled Probit
 - Pooled Logit
- If ϵ serially correlated or X has lags
 - Need to use robust standard errors
- If dynamic completeness
 - Both models work fine
 - Same R functions than for the cross-section (*glm*)

Probability linear model for panel data

Examples of binary responses:

- Choice of transportation mode on day t
- Choice of marital status in year t
- Choice of owning a house in year t
- Being unemployed in week t
- Being in prison in year t

It is common that the same individual has repeated observations over time

- How to deal with that (what are the extra problems)?
- Can we somehow exploit that (besides having more observations)?

Probability linear model for panel data

The simplest panel model is the LPM (without unknown effects):

$$P(y_{jt} = 1 | \mathbf{x}_{jt}) = \mathbf{x}_{jt}\beta$$

- y_{jt} is the choice of individual j in period t
- \mathbf{x}_{jt} are individual characteristics that may vary over time, e.g. age, income, and education
- We can estimate this as we saw before with the POLS.
- Problems? Estimates might be out of $[0,1]$
- Assumptions?

Probability linear model for panel data

LPM with unknown individual effects:

$$P(y_{jt} = 1 | \mathbf{x}_{jt}) = \mathbf{x}_{jt}\boldsymbol{\beta} + c_j$$

- POLS: consistent estimates if c_j is uncorrelated with X but inefficient
 - Solution: RE
- POLS: inconsistent estimates if c_j is correlated with X
 - Solution: FE or FD

However, we will have the same problems than in the cross-sectional case:

Probability linear model for panel data

LPM with unknown individual effects:

$$P(y_{jt} = 1 | \mathbf{x}_{jt}) = \mathbf{x}_{jt}\boldsymbol{\beta} + c_j$$

- POLS: consistent estimates if c_j is uncorrelated with X but inefficient
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- POLS: inconsistent estimates if c_j is correlated with X
 - Solution: FE or FD

However, we will have the same problems than in the cross-sectional case:

Estimates of this probability might be out of $[0,1]$

Any ideas about how to solve this?

Pooled probit and logit

The model **without** individual unknown effects but with panel data:

$$P(y_{jt} = 1 | \mathbf{x}_{jt}) = G(\mathbf{x}_{jt}\boldsymbol{\beta})$$

- $G = \Phi$ – cdf of the normal dist (Probit) or
- $G = \Lambda$ – cdf of the logistic dist (Logit)
- \mathbf{x}_{jt} can contain:
 - Time dummies (e.g. dummies for each year)
 - Time-varying variables (e.g. income for person j)
 - Time-invariant variables (e.g. gender of person j)
 - Cross product of time dummies and time-invariant variables
 - Lagged dependent variables (e.g. labour market status last year) $\Rightarrow Y$'s are correlated over time

Pooled probit and logit

The model:

$$P(y_{jt} = 1 | \mathbf{x}_{jt}) = G(\mathbf{x}_{jt}\boldsymbol{\beta})$$

Estimation problem:

- We don't know the full distribution of (y_{j1}, \dots, y_{jT}) given $(\mathbf{x}_{j1}, \dots, \mathbf{x}_{jT})$
- It could be complicated (multidimensional), as e.g. y_{j1} and y_{j2} could be correlated
- This is a problem when we use maximum likelihood!
- Instead, we apply partial maximum likelihood techniques
- Not in general the same as full maximum likelihood
- But in some cases it is.

Pooled probit and logit

Full conditional maximum likelihood:

- Use full distribution of (y_{j1}, \dots, y_{jT}) given $(\mathbf{x}_{j1}, \dots, \mathbf{x}_{jT})$

Partial maximum likelihood (for each individual):

- Use distribution of y_t given \mathbf{x}_t : $f(y_t|\mathbf{x}_t, \boldsymbol{\beta})$
- The individual likelihood contribution is:

$$\ell_j(\boldsymbol{\beta}) = \sum_{t=1}^T \log f(y_t|\mathbf{x}_t, \boldsymbol{\beta})$$

- This is not necessarily the joint density of y_j , unless the y_{jt} are independent
- Correlated y_{jt} would result in more complicated joint densities

Pooled probit and logit

Example:

$$y_{jt}^* = \mathbf{x}_{jt}\boldsymbol{\beta} + \epsilon_{jt}$$

$$y_{jt} = \mathbf{1}[y_{jt}^* > 0]$$

The partial log-likelihood for observation j is then:

$$\ell_j(\boldsymbol{\beta}) = \sum_{t=1}^T \{y_{jt} \log G(\mathbf{x}_{jt}\boldsymbol{\beta}) + (1 - y_{jt}) \log(1 - G(\mathbf{x}_{jt}\boldsymbol{\beta}))\}$$

And the total partial log-likelihood for the sample:

$$\ell(\boldsymbol{\beta}) = \sum_{j=1}^n \ell_j(\boldsymbol{\beta}) = \sum_{j=1}^n \sum_{t=1}^T \{y_{jt} \log G(\mathbf{x}_{jt}\boldsymbol{\beta}) + (1 - y_{jt}) \log(1 - G(\mathbf{x}_{jt}\boldsymbol{\beta}))\}$$

Which has the same shape as in cross sections \Rightarrow we can use the same command in R for logit/probit (*glm*)

Pooled probit and logit

If **strict exogeneity** is satisfied:

ϵ_{jt} is independent of $\mathbf{x}_{j1}, \dots, \mathbf{x}_{jT}$



ϵ_{jt} are serially independent



y_{jt} are independent conditional on X .



Joint distribution of the y_{jts} is given by the product of the marginal (individual) distributions



Partial ML = full conditional ML

Exercise

We use the data keane.dat before for the probit and logit models:

- $\text{employ} = 1$ if working
- $\text{black} = 1$ if black
- exper : years of experience
- educ : years of education
- each individual recorded from 1981 until 1987.
- Dummies $y81, y82, y83, y84, y85, y86, y87$

Exercise (10 minutes)

Using the `glm` function run the pooled probit model:

- 1 Exogenous variables are *black*, *exper*, *educ*
- 2 As above plus year dummies

Pooled probit and logit

But partial ML works also with weaker assumptions.

Case 1 : ϵ_{jt} may be serially correlated

- Example: when \mathbf{x}_{jt} contains lagged dependent variables (e.g. choice last period) \Rightarrow strict exogeneity is violated

Then pooled probit/logit still provides:

- Consistent estimators
- Asymptotically normal estimators

But the usual standard errors are incorrect due to potential serial correlation

Pooled probit and logit

Case 2 : The model is dynamically complete, i.e. all relevant lags of y and \mathbf{X} are contained in \mathbf{x}_{jt}

Then pooled probit/logit still provides:

- Consistent estimators
- Asymptotically normal estimators

And we can use usual standard errors in this case!

Should we always include lagged variables of exogenous and dependent variables in our model?

- Only if it makes economic sense
- Explaining behaviour today by behaviour yesterday

Pooled probit and logit

A simple test of dynamic completeness:

- 1 Run probit and save residuals $\hat{\epsilon}_{jt} = y_{jt} - \Phi(\mathbf{x}_{jt}\hat{\beta})$
- 2 Run $P(y_{jt} = 1 | \mathbf{x}_{jt}, \hat{\epsilon}_{j,t-1}) = \Phi(\mathbf{x}_{jt}\beta + \lambda\hat{\epsilon}_{j,t-1})$, $t = 2, \dots, T$
- 3 If $\hat{\lambda}$ is significantly zero \Rightarrow then there is dynamic completeness

Binary models with unknown effects

- The previous models are inconsistent
- FE probit model
 - Assumptions (A1)-(A3)
 - Need assumption regarding the dist. of $c_j | \mathbf{x}_j$ to work
- RE probit model
 - Assumptions (A1)-(A4)
- Alternatives to RE probit
 - Pooled probit (A1)+ (A2)+ (A4) \Rightarrow good APE
 - Chamberlain's RE (A1)+ (A2)+ (A3)
- RE logit model (similar to RE probit)
- FE logit model
 - Assumptions (A1)-(A3)
 - Consistent estimates

Probit with unobserved effects

We have seen that if we assumed **no** unobserved individual effects, $c_j \Rightarrow$ we could use pooled probit/logit

However unobserved effects are likely to be important

Examples:

- Individual taste affects choice of transportation, choice of marriage, etc
- Individual ability affects risk of unemployment
- Unobservable characteristics affect risk of being in prison

Thus, in many cases we should allow for such unobservable effects

Probit with unobserved effects

Now the model is:

$$P(y_{jt} = 1 | \mathbf{x}_{jt}, c_j) = \Phi(\mathbf{x}_{jt}\boldsymbol{\beta} + c_j) \quad t = 1, \dots, T$$

Assumptions:

- (A1) c_j is an unobserved (individual) effect
- (A2) Strict exogeneity of \mathbf{x}_{jt} conditional on c_j
 - No lagged variables in X
 - $E(\mathbf{x}_{js}\epsilon_{jt}) = 0$ for $s, t = 1, \dots, T$
- (A3) y_{j1}, \dots, y_{jT} are independent conditional on \mathbf{x}_j and c_j

Probit with unobserved effects

Under (A1)-(A3), the joint density of y_{j1}, \dots, y_{jT} is the product of the marginal densities:

$$f(y_1, \dots, y_T | \mathbf{x}_j, c_j; \boldsymbol{\beta}) = \prod_{t=1}^T f(y_t | \mathbf{x}_{jt}, c_j; \boldsymbol{\beta})$$

Where:

$$f(y_t | \mathbf{x}_t, c; \boldsymbol{\beta}) = [\Phi(\mathbf{x}_t \boldsymbol{\beta} + c)]^{y_t} [1 - \Phi(\mathbf{x}_t \boldsymbol{\beta} + c)]^{1-y_t}$$

How to estimate this model?

Probit with unobserved effects

$$f(y_1, \dots, y_T | \mathbf{x}_j, c_j; \beta) = \prod_{t=1}^T f(y_t | \mathbf{x}_{jt}, c_j; \beta)$$

1) FE probit estimation:

- We can't get rid of the c_j by differencing as in linear models
- Then, we have to estimate c_j along with β
- An incidental parameters problem: we get inconsistent estimates of β if we have to estimate too many c_j
- No restrictions on relationship between c_j and \mathbf{x}_{jt} (one would be needed)
- It tends to give very biased results

Probit with unobserved effects

$$f(y_1, \dots, y_T | \mathbf{x}_j, c_j; \boldsymbol{\beta}) = \prod_{t=1}^T f(y_t | \mathbf{x}_{jt}, c_j; \boldsymbol{\beta})$$

2) RE probit estimation:

- We need to make an additional assumption about c_j and \mathbf{x}_j :
(A4)
 - Independence of c_j and \mathbf{x}_j and
 - c_j is random
 - $c_j | \mathbf{x}_j \sim N(0, \sigma_c^2)$
- These are very strong assumptions

Probit with unobserved effects

$$f(y_1, \dots, y_T | \mathbf{x}_j, c_j; \beta) = \prod_{t=1}^T f(y_t | \mathbf{x}_{jt}, c_j; \beta)$$

2) RE probit estimation:

- Under (A1)-(A4), we can integrate c_j 's out of the log-likelihood function i.e. find joint density that does not depend on c_j :

$$\begin{aligned} \ell_j(\beta, \sigma_c) &= \log(f(y_{j1}, \dots, y_{jT} | \mathbf{x}_{j1}, \dots, \mathbf{x}_{jT}; \beta, \sigma_c^2)) \\ &= \int \left[\prod_{t=1}^T f(y_{jt} | \mathbf{x}_{j1}, \dots, \mathbf{x}_{jT}, c; \beta) \right] \underbrace{\frac{1}{\sigma_c} \phi\left(\frac{c}{\sigma_c}\right) dc}_{\text{density of } c_j} \end{aligned}$$

- $\ell(\beta, \sigma_c) = \sum_{j=1}^n \ell_j(\beta, \sigma_c)$
- Log-lik is maximised wrt β and σ_c

Probit with unobserved effects

Alternatives to RE estimation (relaxing some of the assumptions):

A) Pooled probit, (A1)+(A2)+(A4)

$$P(y_{jt} = 1 | \mathbf{x}_{jt}) = \Phi(\mathbf{x}_{jt}\boldsymbol{\beta})$$

- Error term is then: $c_j + \epsilon_{jt}$ with variance: $1 + \sigma_c^2$
- We estimate $\beta_c = \frac{\boldsymbol{\beta}}{\sqrt{1 + \sigma_c^2}}$
- β_c is enough to compute APE for \mathbf{x}_{tj} :

$$\frac{\beta_j}{\sqrt{1 + \sigma_c^2}} \phi \left(\frac{\mathbf{x}_t \boldsymbol{\beta}}{\sqrt{1 + \sigma_c^2}} \right)$$

NB serial correlation due to $c_j \Rightarrow$ use eq. (13.53) to compute standard errors

Probit with unobserved effects

Alternatives to RE estimation (relaxing some of the assumptions):

B) Assume particular correlation structure for the ϵ_{jt} 's,

(A1)+(A2)+(A4)

- Hard to estimate in practice.

C) Chamberlain's random effects model (A1)+(A2)+(A3)

- Relaxes assumption that c_j is independent of \mathbf{x}_j
- (A4).2 Specify distribution of c_j given \mathbf{x}_j (some dependence):

$$c_j = \Psi + \bar{\mathbf{x}}_j \xi + a_j \quad a_j | \mathbf{x}_j \sim N(0, \sigma_a^2)$$

- Hence the latent variable is: $y_{jt}^* = \Psi + \mathbf{x}_{jt} \beta + \bar{\mathbf{x}}_j \xi + a_j + \epsilon_{jt}$
- This is just a RE probit $P(y_{jt} = 1 | \mathbf{x}_{jt}, c_j) = \Phi(\Psi + \mathbf{x}_{jt} \beta + \bar{\mathbf{x}}_j \xi)$

Logit with unobserved effects

The model is similar to the probit case:

$$P(y_{jt} = 1 | \mathbf{x}_{jt}, c_j) = \Lambda(\mathbf{x}_{jt}\boldsymbol{\beta} + c_j)$$

Assumptions:

- (A1) c_j is an unobserved (individual) effect
- (A2) Strict exogeneity of \mathbf{x}_{jt} conditional on c_j
- (A3) y_{j1}, \dots, y_{jT} are independent conditional on \mathbf{x}_j and c_j
- (A4) $c_j | \mathbf{x}_j \sim N(0, \sigma_c^2)$

Logit with unobserved effects

Under A1-A4:

- The RE logit model
- Similar in principle to RE probit
- But much tougher to estimate \Rightarrow less used

Under A1-A3:

- The FE logit model
- Similar in principle to FE probit
- But (as opposed to probit), it yields consistent estimates

Logit with unobserved effects

The FE logit model - the idea:

- We can derive joint distribution of y_{j1}, \dots, y_{jT} that does not depend on c_j 's.
- But it depends on $n_j = \sum_{t=1}^T y_{jt}$ (# successes for person j)

Example:

- Assume $T = 2$ (two periods)
- Hence, n_j is either 0, 1 or 2
- We must derive conditional joint distribution of y_{j1} and y_{j2}

Logit with unobserved effects

Example:

- If $n_j = 0$, i.e. $y_{j1} = 0$ and $y_{j2} = 0$
 - Person j yields no information about β
 - With fixed effects, we need variation within a person
-
- If $n_j = 2$, i.e. $y_{j1} = 1$ and $y_{j2} = 1$
 - Same, person j yields no information about β
 - Only when $n_j = 1$, is person j informative about parameters in β

Logit with unobserved effects

Example:

If $n_j = 1$, there are two possibilities:

- ① $y_{j1} = 0$ and $y_{j2} = 1$ or
- ② $y_{j1} = 1$ and $y_{j2} = 0$

Consider case 1:

$$\begin{aligned}
 P(y_{j1} = 0, y_{j2} = 1 | \mathbf{x}_j, c_j, n_j = 1) &= \frac{P(y_{j1} = 0 | \mathbf{x}_j, c_j) P(y_{j2} = 1 | \mathbf{x}_j, c_j)}{P(n_j = 1 | \mathbf{x}_j, c_j)} \\
 &= \frac{P(y_{j1} = 0 | \mathbf{x}_j, c_j) P(y_{j2} = 1 | \mathbf{x}_j, c_j)}{P(y_{j1} = 0, y_{j2} = 1 | \mathbf{x}_j, c_j) + P(y_{j1} = 1, y_{j2} = 0 | \mathbf{x}_j, c_j)} \\
 &= \Lambda((\mathbf{x}_{j2} - \mathbf{x}_{j1})\boldsymbol{\beta})
 \end{aligned}$$

Logit with unobserved effects

It can be derived that:

$$P(y_{j1} = 0, y_{j2} = 1 | \mathbf{x}_j, c_j, n_j = 1) = \Lambda((\mathbf{x}_{j2} - \mathbf{x}_{j1})\boldsymbol{\beta})$$

And hence:

$$P(y_{j1} = 1, y_{j2} = 0 | \mathbf{x}_j, c_j, n_j = 1) = 1 - \Lambda((\mathbf{x}_{j2} - \mathbf{x}_{j1})\boldsymbol{\beta})$$

And these do not depend on c_j !

Logit with unobserved effects

The log-lik then becomes:

$$\ell_j(\beta) = \mathbf{1}[n_j = 1] \{w_j \log \Lambda((\mathbf{x}_{j2} - \mathbf{x}_{j1})\beta) + (1 - w_j) \log(1 - \Lambda((\mathbf{x}_{j2} - \mathbf{x}_{j1})\beta))\}$$

Note that:

- $w_j = 1$ if $y_{j1} = 0$ and $y_{j2} = 1$
- $w_j = 0$ if $y_{j1} = 1$ and $y_{j2} = 0$
- Observations with $n_j = 0$ or $n_j = 2$ do not contribute to log-lik
- Log-lik does not depend on c_j , only n_j (which is observed)
- We use change in X to explain change in behaviour

Logit with unobserved effects

- For $T > 2$, the log-lik is more complicated to derive, but the principle is the same
- c_j can be eliminated from joint distribution (and from the log-lik), see (15.73)
- Then we can maximise the log-lik without having to estimate the c_j 's
- I.e. much like differencing in the linear panel data model.

NB!

We don't estimate the c_j 's, but c_j 's are needed to calculate partial effects and average partial effects! \Rightarrow we must calculate these for some choice of c_j !

Dynamic binary models with unknown effects

- Condition (A2) ruled out lagged variables
- Dynamic unobserved effect models allow them
- RE probit with additional explanatory variables

Dynamic Unobserved Effects Models

The Probit and Logit models with unobserved effects require strict exogeneity of \mathbf{x}_{jt} conditional on c_j

- I.e. errors uncorrelated with X 's from all other periods
- This rules out lagged endogenous variables,
 - Example: If $\mathbf{x}_{jt} = y_{j,t-1}$ then \mathbf{x}_{jt} is correlated with $\epsilon_{j,t-1}$
- But sometimes, we want to include lagged endogenous on the RHS
- We could do that in the absence of unobserved effects, c_j
- But what happens when c_j is present?

Dynamic Unobserved Effects Models

Example:

$$P(y_{jt} = 1 | y_{j,t-1}, y_{j,t-2}, \dots, y_{j0}, Z_{jt}, c_j) = G(Z_{jt}\delta + \rho y_{j,t-1} + c_j)$$

- Probability depends on event last period
- Probability of being in prison in year $t - 1$
- Probability of smoking in week $t - 1$
- Probability of watching Paradise Hotel on day $t - 1$

These events all exhibit *State Dependence*

- What you do today depends on what you did yesterday
- And in these cases state dependence makes economic sense

Dynamic Unobserved Effects Models

$$P(y_{jt} = 1 | y_{j,t-1}, y_{j,t-2}, \dots, y_{j0}, Z_{jt}, c_j) = G(Z_{jt}\delta + \rho y_{j,t-1} + c_j)$$

Note:

- G can be probit or logit
- Z_{jt} satisfies strict exogeneity assumption conditional on c_j
- Lagged endogenous variable \Rightarrow violates strict exogeneity (error in $t - 1$ is correlated explanatory variables in t)
- $H_A : \rho \neq 0$, i.e. state dependence after controlling for c_j ?
- How do we estimate δ and ρ ?

Dynamic Unobserved Effects Models

$$P(y_{jt} = 1 | y_{j,t-1}, y_{j,t-2}, \dots, y_{j0}, Z_{jt}, c_j) = G(Z_{jt}\delta + \rho y_{j,t-1} + c_j)$$

The joint density:

$$f(y_{jt}, \dots, y_{jT} | y_{j0}, Z_{jt}, c_j) = \prod_{t=1}^T G(Z_{jt}\delta + \rho y_{j,t-1} + c_j)^{y_{jt}} [1 - G(Z_{jt}\delta + \rho y_{j,t-1} + c_j)]^{1-y_{jt}}$$

- To estimate this, we need to integrate out the c_j 's (as in the RE models)
- But first we must figure out what to do about the y_{j0} (the initial conditions problem)?

Dynamic Unobserved Effects Models

Several solutions available:

- 1 Treat y_{j0} as a non-stochastic starting value for each person, and assume a distribution of c_j given Z_j to integrate out the c_j 's
 - we implicitly assume that c_j and y_{j0} are independent
- 2 Specify a density for y_{j0} given Z_j and c_j , and multiply it on the joint density from previous slide
 - Distribution of $y_{j0}, y_{j1}, \dots, y_{jT}$ given Z_j and c_j
 - But where does this density come from?
 - For example Heckman (1981) assumes a probit for y_{j0} given Z_j and c_j
 - Then he assumes c_j given Z_j is normal \Rightarrow we can integrate out the c_j 's

Dynamic Unobserved Effects Models

Several solutions available:

- 3 Condition on $y_{j0} \Rightarrow$ we need distribution of c_j given y_{j0} and Z_j

- Example:

$$c_j = \Psi + \xi_0 y_{j0} + \xi Z_j + a_j \quad a_j \sim N(0, \sigma_a^2)$$

- Where a_j is independent of y_{j0} and $Z_j \Rightarrow$
- Resulting model is:

$$y_{jt} = \mathbf{1} [\Psi + Z_{jt}\delta + \rho y_{j,t-1} + \xi_0 y_{j0} + \xi Z_j + a_j + \epsilon_{jt} > 0]$$

Dynamic Unobserved Effects Models

$$y_{jt} = \mathbf{1} [\Psi + Z_{jt}\delta + \rho y_{j,t-1} + \xi_0 y_{j0} + \xi Z_j + a_j + \epsilon_{jt} > 0]$$

This model can be estimated as a RE probit:

- $Z_{jt}, y_{j,t-1}, y_{j0}$ and Z_j are the explanatory variables
- a_j is the random effect (normally distributed and independent of the explanatory variables)
- This is simply a RE probit with additional explanatory variables.
- how would you do it in R?

Logit RE in R

- package: lme4
- function: glmer
- syntax:
`glmer (y~1 + X + (1|subject), data=data,
family=binomial("logit"))`

Summary

- Panel data on binary choices
 - If no unobserved effect \Rightarrow pooled probit and logit can be used
 - Also with serial correlation
- If unobserved effect and strict exogeneity
 - FE: allows for correlation with X , but only works in logit case
 - RE: does not allow for correlation (more restrictive)
- If unobserved effect + lagged endogenous variable
 - Dynamic unobserved effects models
 - This is basically a RE estimation with additional explanatory variables